



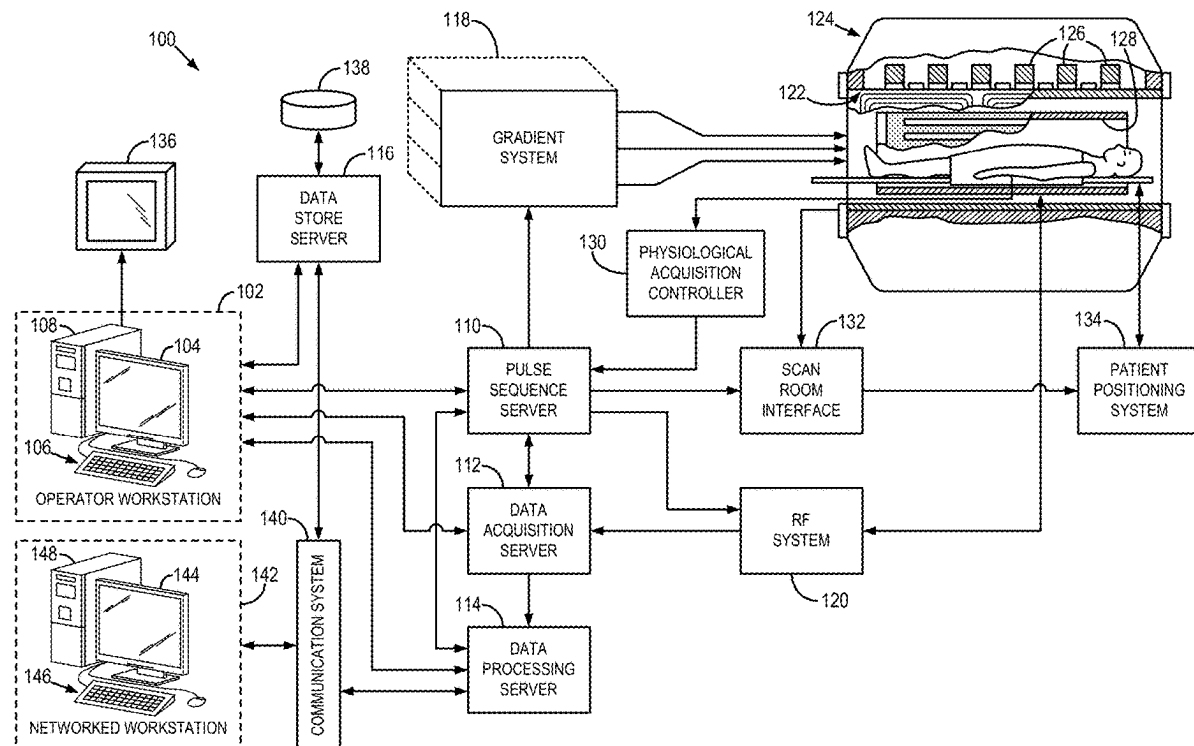
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(19) **United States**(12) **Patent Application Publication****Tamada et al.**(10) **Pub. No.: US 2025/0102607 A1**(43) **Pub. Date: Mar. 27, 2025**(54) **SYSTEM AND METHOD FOR CONFIDENCE MAPS FOR QUANTITATIVE MAPPING WITH MAGNETIC RESONANCE IMAGING**(52) **U.S. Cl.**CPC **G01R 33/5608** (2013.01); **G01R 33/543** (2013.01); **G01R 33/5654** (2013.01)(71) Applicant: **Wisconsin Alumni Research Foundation**, Madison, WI (US)

(57)

ABSTRACT(72) Inventors: **Daiki Tamada**, Madison, WI (US);
Scott Reeder, Middleton, WI (US)(21) Appl. No.: **18/473,862**(22) Filed: **Sep. 25, 2023****Publication Classification**(51) **Int. Cl.****G01R 33/56** (2006.01)**G01R 33/54** (2006.01)**G01R 33/565** (2006.01)

A system and method are provided for generating at least one confidence map indicating the accuracy of a quantitative map generated from magnetic resonance (MR) data acquired from a subject. The method includes accessing at least one of proton density fat fraction (PDFF) or R_2^* maps of a region of interest (ROI) of a subject produced using chemical-shift encoded magnetic resonance (MR) data acquired from the ROI in the subject, generating at least one confidence map that indicates an accuracy of the at least one of the PDFF or R_2^* maps, and outputting at least one of (i) the at least one confidence map or (ii) a corrected PDFF or R_2^* map that is corrected using the at least one confidence map.



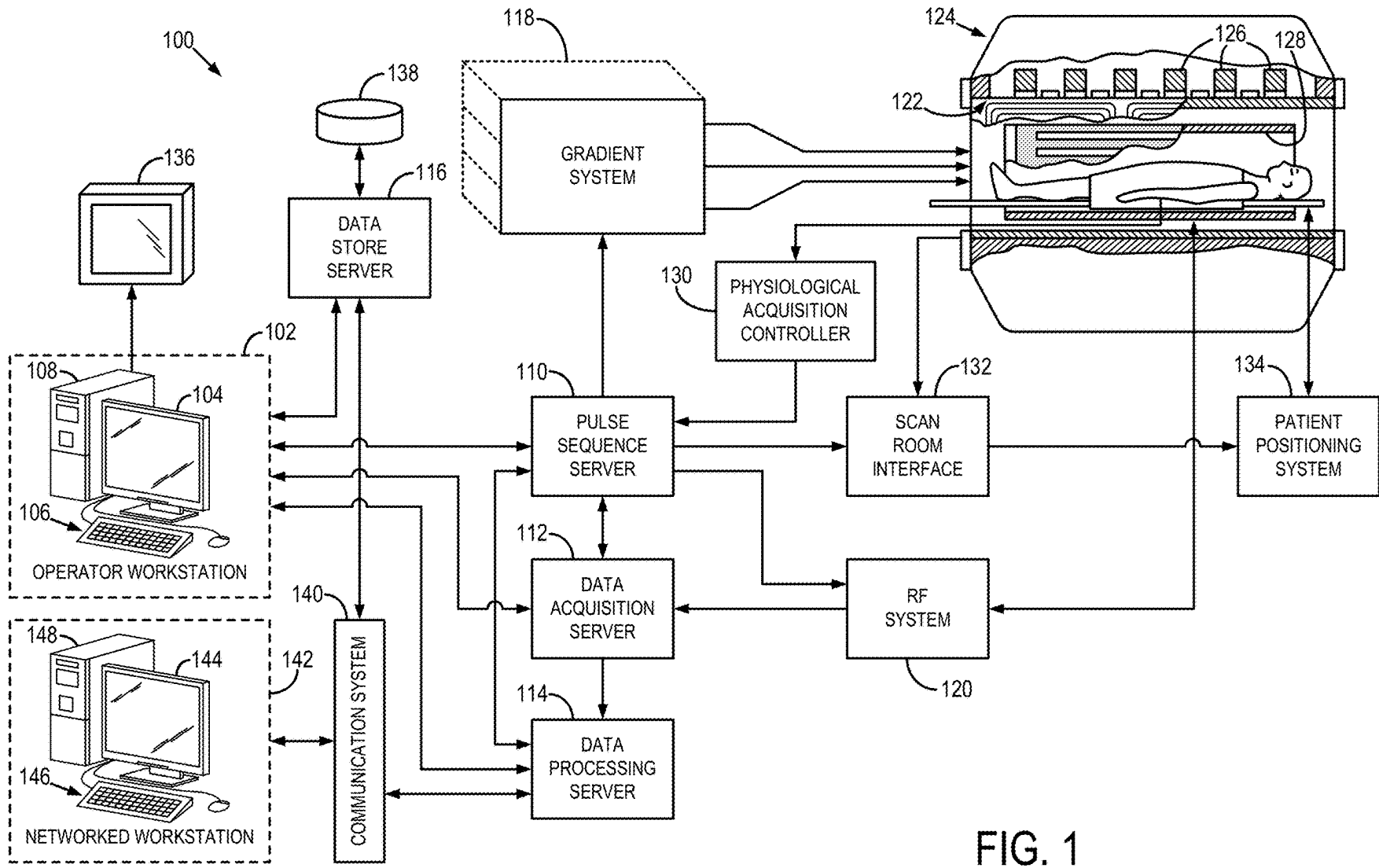
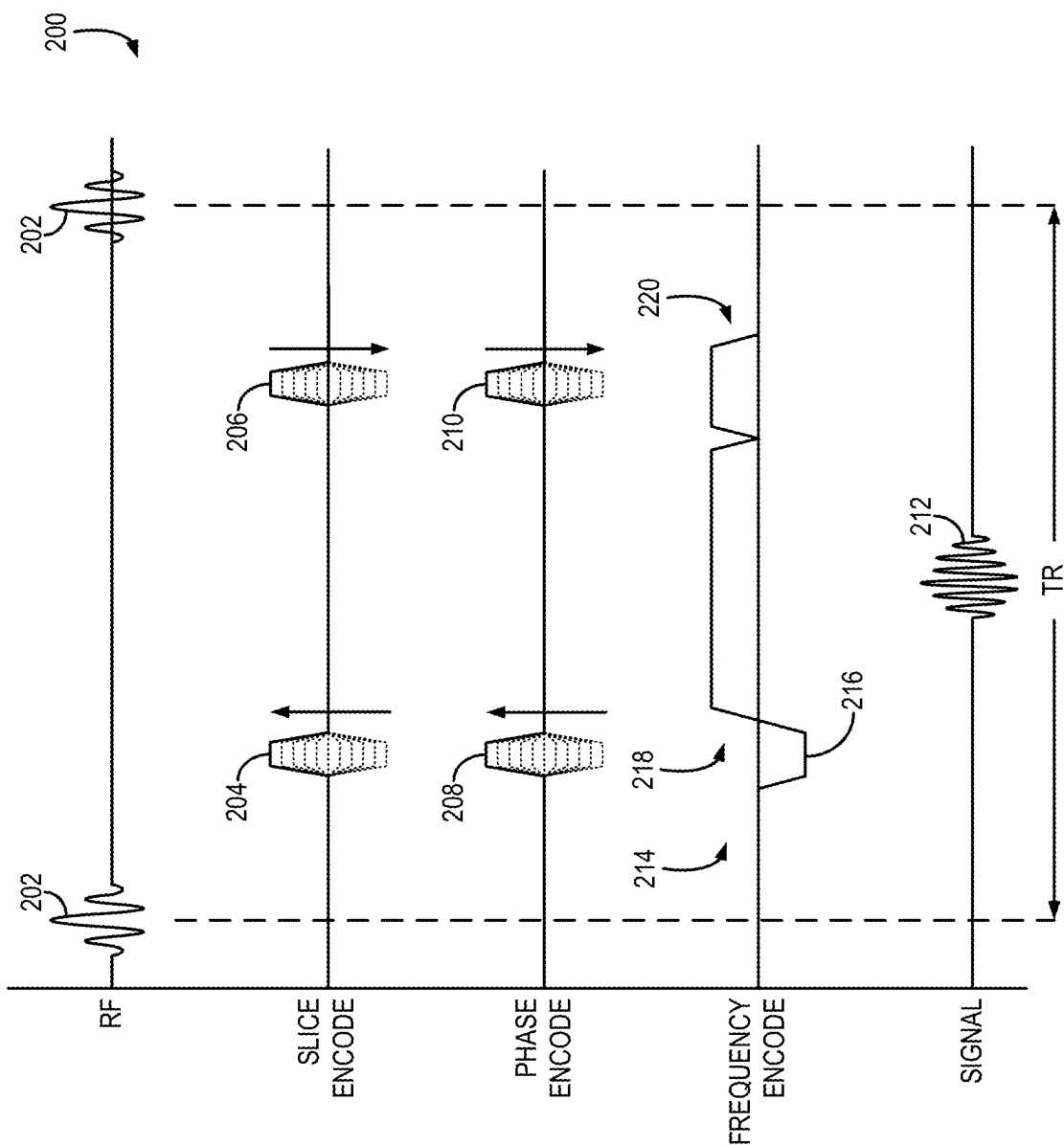


FIG. 1

FIG. 2



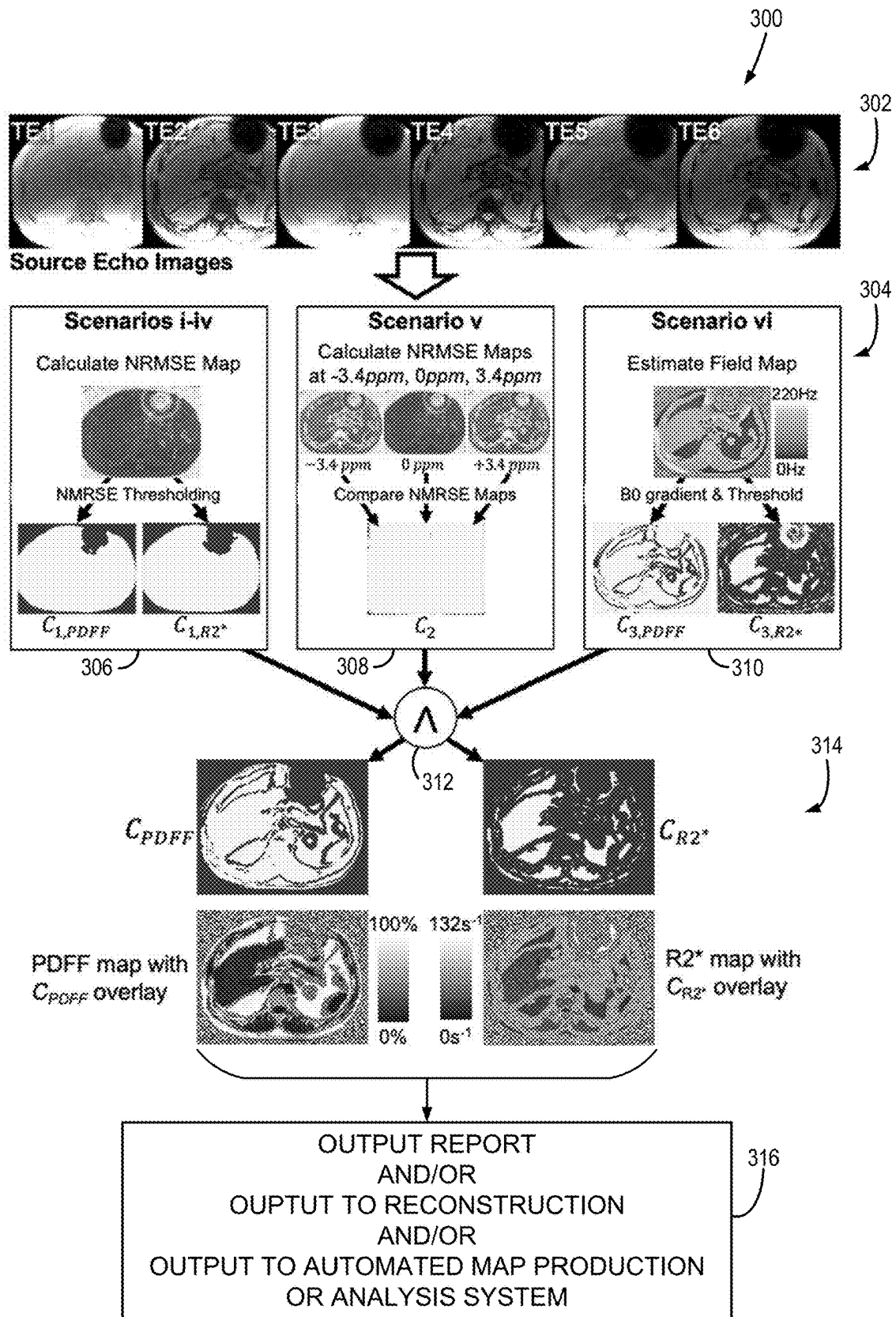


FIG. 3

FIG. 4A

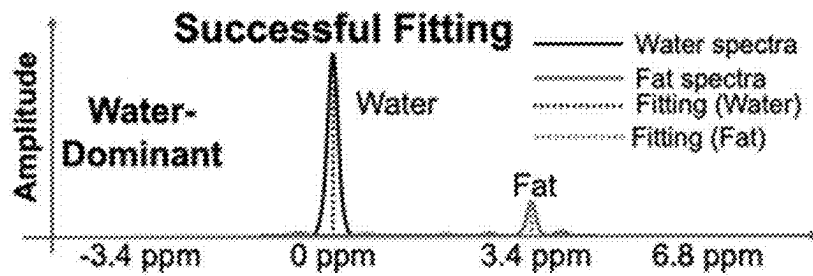


FIG. 4B

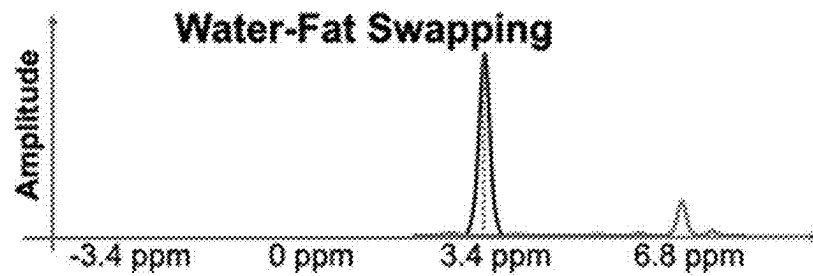


FIG. 4C

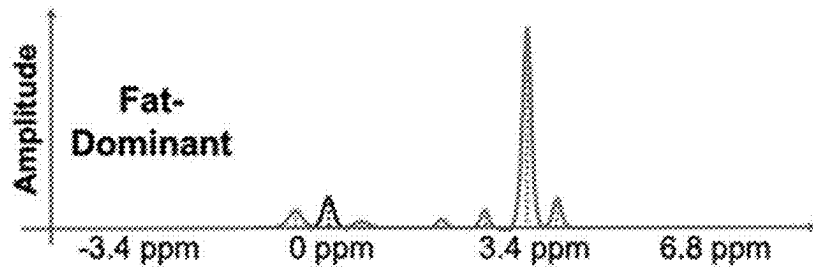


FIG. 4D

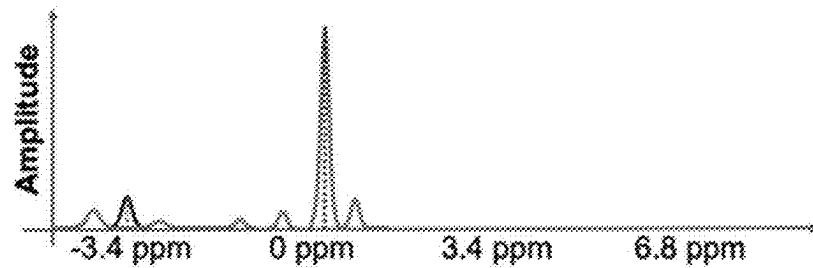


FIG. 5A

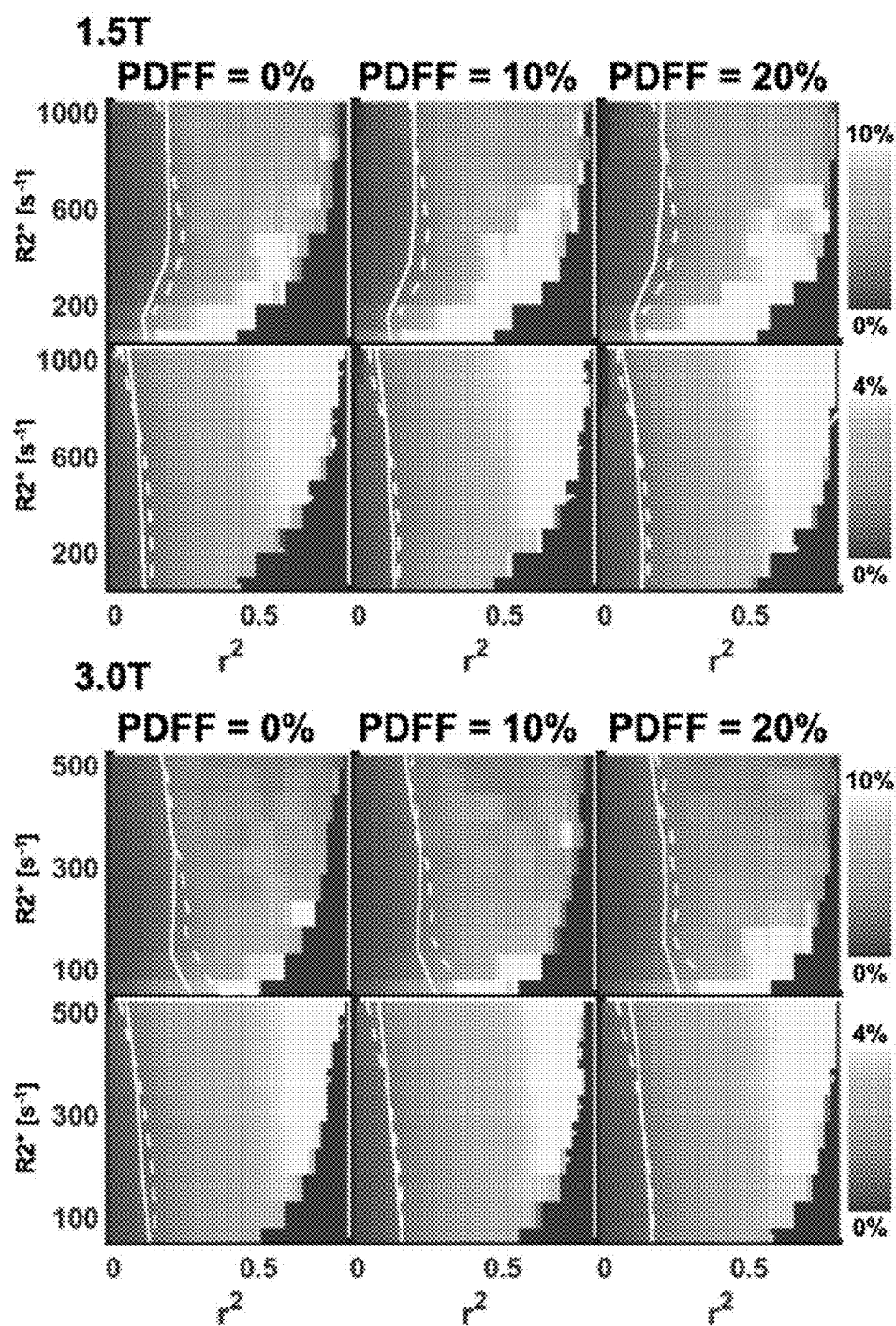


FIG. 5B

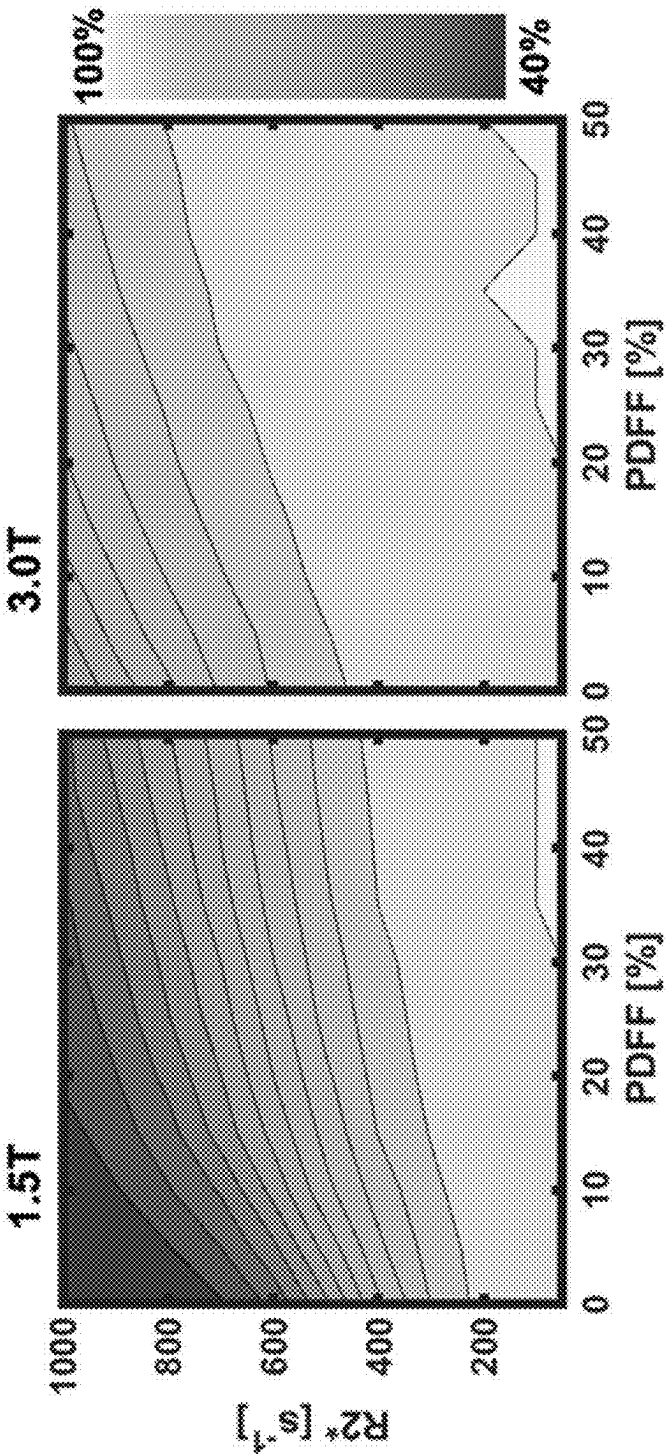


FIG. 6A

FIG. 6B

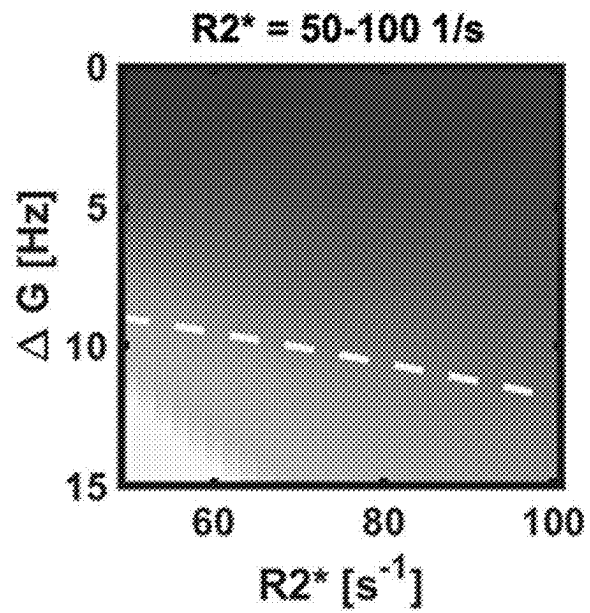


FIG. 7A

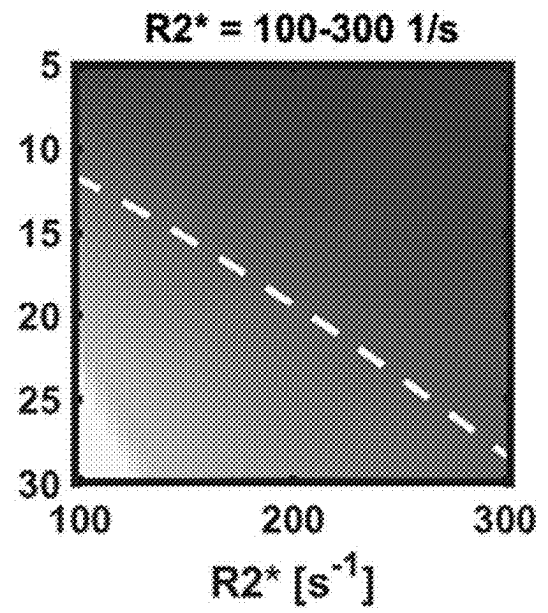


FIG. 7B

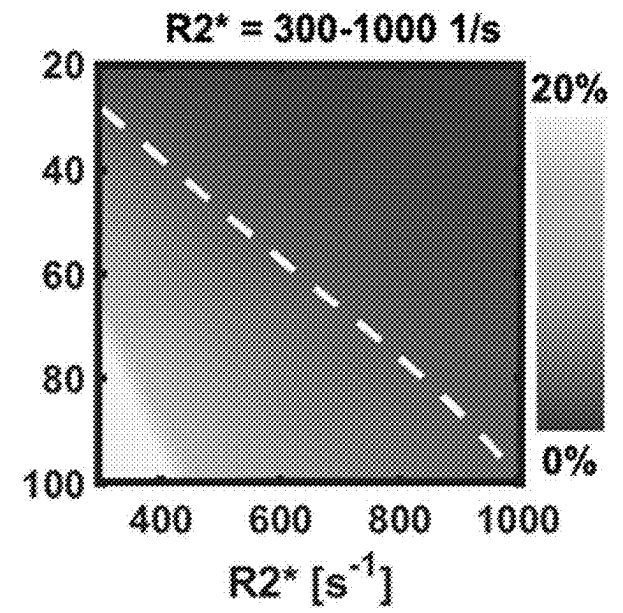


FIG. 7C

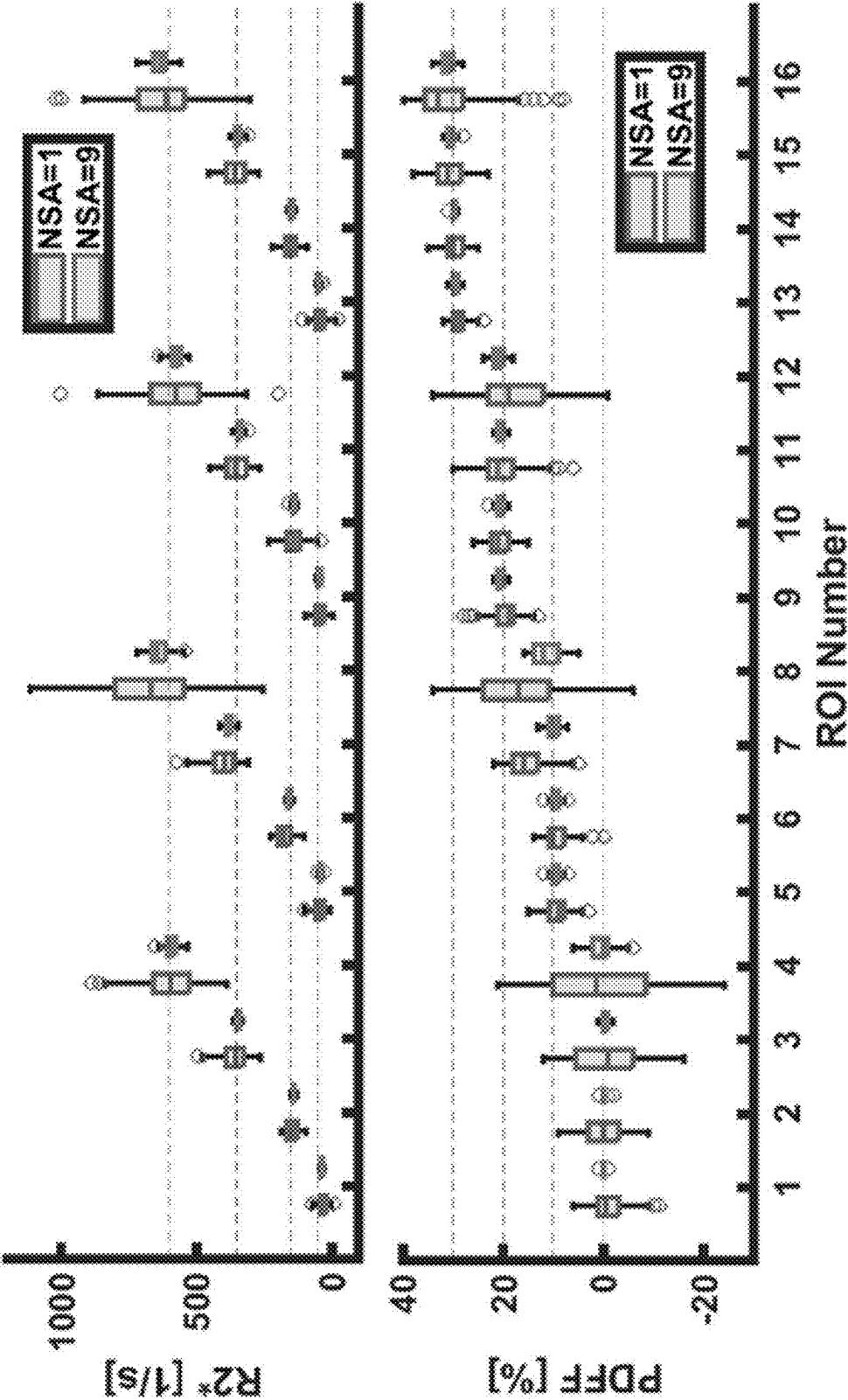


FIG. 8

SYSTEM AND METHOD FOR CONFIDENCE MAPS FOR QUANTITATIVE MAPPING WITH MAGNETIC RESONANCE IMAGING

STATEMENT REGARDING FEDERALLY SPONSORED RESEARCH

[0001] N/A

BACKGROUND

[0002] The field of the disclosure is systems and methods for magnetic resonance imaging (MRI). More particularly, the disclosure relates to systems and methods for creating confidence maps for quantitative maps produced using magnetic resonance imaging.

[0003] When a substance, such as human tissue, is subjected to a uniform magnetic field (polarizing field B_0), the individual magnetic moments of the nuclei in the tissue attempt to align with this polarizing field, but precess about it in random order at their characteristic Larmor frequency. If the substance, or tissue, is subjected to a magnetic field (excitation field B_1) that is in the x-y plane and that is near the Larmor frequency, the net aligned moment, M_z , may be rotated, or “tipped”, into the x-y plane to produce a net transverse magnetic moment, M_{xy} . A signal is emitted by the excited nuclei or “spins”, after the excitation signal B_1 is terminated, and this signal may be received and processed to form an image.

[0004] When utilizing these “MR” signals to produce images, magnetic field gradients (G_x , G_y , G_z) are employed. Typically, the region to be imaged is scanned by a sequence of measurement cycles in which these gradients vary according to the particular localization method being used. The resulting set of received MR signals are digitized and processed to reconstruct the image using one of many well-known reconstruction techniques.

[0005] To do so, the signals are often weighted in different ways to give preference to or consider different sub-signals or so-called contrast mechanisms. Two basic “contrast mechanisms” commonly utilized in MR imaging are the spin-lattice (or longitudinal or T_1) relaxation time or spin-spin (or transverse or T_2) relaxation time. The T_1 and T_2 contrast mechanism are the two most important relaxation mechanisms commonly exploited to provide soft tissue contrast in clinical MRI examinations. Both T_1 - and T_2 -weighted acquisitions play a ubiquitous role in almost every clinical MRI exam and are important for a variety of applications including lesion detection, characterization, treatment monitoring, and many other applications. However, there are a variety of other mechanisms for eliciting contrast in MRI, including transverse relaxivity rate (R_2^*). Specifically, R_2^* is the inverse of T_2^* , which is a quantity related to T_2 , but includes dephasing effects. That is, T_2^* is a quantity related to spin-spin relaxation and, in addition, relating magnetic field inhomogeneities and susceptibility effects.

[0006] These contrast mechanisms can be manipulated by selecting particular imaging parameters utilized while performing a pulse sequence to acquire MR data, so that the images reconstructed from the MR data reflect a particular weighting toward the preferred contrast mechanism that best illustrate the underlying anatomy or pathology that is the focus of the clinical analysis. Since the fundamentals of the pulse sequence and the imaging parameters dictate the

contrast weighting, a variety of different pulse sequences and variations on pulse sequences have been developed.

[0007] Beyond controlling these contrast mechanisms for purposes of creating anatomical images, which convey qualitative information about the illustrated anatomical structures via the relative contrast in the images, there have been concerted efforts to elicit quantitative information from MR data. For example, instead of qualitative images, some have created quantitative maps using MR data.

[0008] As examples, quantitative T_1 and T_2 mapping have gained attention as a promising approach for the diagnosis and evaluation of various diseases. Proton density fat-fraction (PDFF) and R_2^* estimated using quantitative chemical shift-encoded MRI (CSE-MRI) are well-established quantitative biomarkers of liver fat content. As such, CSE-MRI methods are FDA-approved to evaluate diseases such as non-alcoholic fatty liver disease and liver iron overload. More recently, R_2^* mapping with CSE-MRI been shown to be reproducible across vendors and calibrated to liver iron concentration (LIC, mgFe/g dry).

[0009] Despite these efforts, reliable estimation of PDFF and R_2^* remains a challenge because of confounding factors, such as low signal-to-noise ratio (SNR), high iron content, inhomogeneous main magnetic field (B_0), and motion. For example, Colgan T J, Zhao R, Roberts N T, Hernando D, Reeder S B. Limits of Fat Quantification in the Presence of Iron Overload. J Magn Reson Imaging 2021; 54(4):1166-1174 investigated the reliability of PDFF estimation in the presence of high R_2^* , showing that PDFF measurements may be unreliable above R_2^* of $\sim 500 \text{ s}^{-1}$ and $\sim 800 \text{ s}^{-1}$ at 1.5T and 3.0T, respectively.

[0010] With low SNR, PDFF estimates demonstrate not only high variability but also bias, due to an asymmetric noise probability density at low SNR. Phase errors caused by hardware imperfections and concomitant field gradients, also introduce bias and poor reliability of PDFF and R_2^* estimation. Further, water-fat swapping can occur in areas of high B_0 inhomogeneity, such as the liver dome. Despite sophisticated methods aimed at preventing water-fat swaps, such swaps remain a challenge, even with commercial methods. Incorrect estimation of the B_0 field results from a natural ambiguity in the water and fat signals in water (fat)-dominant pixels, leading to incorrect estimation or quantification of both PDFF and R_2^* . Ghosting of adipose tissue signal into the liver can also lead to inaccurate estimation of PDFF and R_2^* .

[0011] Unbiased estimation of PDFF and R_2^* is needed clinically for accurate diagnosis, staging, and treatment monitoring. For example, differentiation of normal liver from biopsy-based grade 1 hepatic steatosis occurs at a PDFF threshold of ~ 5.4 - 6.4% . Unfortunately, most commercial and investigational CSE-MRI methods simply provide reconstructed PDFF and R_2^* maps without any guidance on regions with valid PDFF and/or R_2^* fitting. Regions with inadequate or corrupted estimates of PDFF or R_2^* are often not apparent, even to experienced human analysts.

[0012] Algorithms that segment the liver are emerging and hold promise for automated PDFF and R_2^* analysis, making automated identification of valid regions necessary. Without automated methods to exclude invalid regions of PDFF and R_2^* maps, the performance of fully automated analysis of PDFF and R_2^* mapping may be limited.

[0013] Therefore, there is a continuing need to provide accurate and understandable PDFF and R_2^* maps that can be used for clinical diagnosis and care.

SUMMARY

[0014] The present disclosure overcomes the aforementioned drawbacks by providing systems and methods for generating confidence maps that identify regions in quantitative maps (such as, for example, PDFF and R_2^* maps) that are valid for subsequent analysis by clinicians and/or automated algorithms. As such, clinical care is substantially improved by providing clinicians with the information needed to be certain that quantitative maps can be trusted, either for clinician analysis or automated processing.

[0015] In accordance with one aspect of the disclosure, a magnetic resonance imaging (MRI) system is provided that includes a magnet system configured to generate a polarizing magnetic field about at least a portion of a subject arranged in the MRI system and a plurality of gradient coils configured to apply magnetic gradients to the polarizing magnetic field. The MRI system further includes a radio frequency (RF) system configured to apply an excitation field to the subject and acquire MR image data from the subject and a computer system. The computer system is programmed to control the plurality of gradient coils and the RF system to perform a multi-echo gradient echo pulse sequence to acquire chemical-shift encoded magnetic resonance (MR) data from a region of interest (ROI) in the subject and estimate at least one of proton density fat fraction (PDFF) or R_2^* in the ROI using the MR data. The computer system is further programmed to generate at least one confidence map that indicates an accuracy of the estimate of the at least one of the PDFF or R_2^* in the ROI. The system also includes a display to display one of (i) the at least one confidence map or (ii) a PDFF or R_2^* map corrected using the at least one confidence map.

[0016] In accordance with another aspect of the disclosure, a method is provided for generating at least one confidence map indicating the accuracy of a quantitative map generated from magnetic resonance (MR) data acquired from a subject. The method includes accessing, using a computer system, at least one of a proton density fat fraction (PDFF) map or R_2^* map produced from the MR data and processing, using the computer system, the at least one of the PDFF map or R_2^* map using a threshold to identify spatial locations in the PDFF map or R_2^* map with at least one of poor quality of signals for PDFF or R_2^* measurements or water-fat swaps. The method further includes communicating, using the computer system, a report including at least one of (i) the spatial locations with poor quality of signals for PDFF or R_2^* measurements or water-fat swaps or (ii) a PDFF or R_2^* map corrected using the spatial locations with poor quality of signals for PDFF or R_2^* measurements or water-fat swaps.

[0017] In accordance with yet another aspect of the disclosure, a non-transitory, computer-readable storage medium is provided having stored thereon instructions that, when executed by a computer processor, causes the computer processor to carry out steps. The steps includes accessing at least one of proton density fat fraction (PDFF) or R_2^* maps of a region of interest (ROI) of a subject produced using chemical-shift encoded magnetic resonance (MR) data acquired from the ROI in the subject, generating at least one confidence map that indicates an accuracy of the at least one

of the PDFF or R_2^* maps, and outputting at least one of (i) the at least one confidence map or (ii) a corrected PDFF or R_2^* map that is corrected using the at least one confidence map.

[0018] The foregoing and other aspects and advantages of the invention will appear from the following description. In the description, reference is made to the accompanying drawings, which form a part hereof, and in which there is shown by way of illustration a preferred embodiment of the invention. Such embodiment does not necessarily represent the full scope of the invention, however, and reference is made therefore to the claims and herein for interpreting the scope of the invention.

BRIEF DESCRIPTION OF THE DRAWINGS

[0019] FIG. 1 is a block diagram of an exemplary magnetic resonance imaging (MRI) system configured in accordance with the present disclosure.

[0020] FIG. 2 is a graphic representation of an exemplary pulse sequence for directing the MRI system of FIG. 1 in accordance with the present disclosure.

[0021] FIG. 3 is a graphical flow chart setting forth some non-limiting steps of a method for generating confidence maps in accordance with the present disclosure.

[0022] FIG. 4A is a graph showing a successful water-dominant fitting using a multi-peak signal model.

[0023] FIG. 4B is a graph showing an unsuccessful water-dominant fitting using a multi-peak signal model.

[0024] FIG. 4C is a graph showing a successful fat-dominant fitting using a multi-peak signal model.

[0025] FIG. 4D is a graph showing an unsuccessful fat-dominant fitting using a multi-peak signal model.

[0026] FIG. 5A is a plot showing a set of PDFF and R_2^* thresholds for NMRSE at 1.5T.

[0027] FIG. 5B is a plot showing a set of PDFF and R_2^* thresholds for NMRSE at 3.0T.

[0028] FIG. 6A is a plot showing a probability of water-fat swapping as a function of PDFF and R_2^* for 1.5T.

[0029] FIG. 6B is a plot showing a probability of water-fat swapping as a function of PDFF and R_2^* for 3.0T.

[0030] FIG. 7A is a plot of bias in percentage of R_2^* measurement as a function of field gradient and R_2^* showing that, at lower value of R_2 , a relatively small field gradient could provide non-negligible bias.

[0031] FIG. 7B is a plot of bias in percentage of R_2^* measurement as a function of field gradient and R_2^* showing a medium value of R_2 .

[0032] FIG. 7C is a plot of bias in percentage of R_2^* measurement as a function of field gradient and R_2^* showing that, at a high- R_2^* range, bias could be neglected regardless of the field gradient.

[0033] FIG. 8 is a set of box plots for PDFF and R_2^* showing the median, first/third quartile, and minimum/maximum values for each vial in a phantom study.

DETAILED DESCRIPTION

[0034] Referring now to FIG. 1, a magnetic resonance imaging (MRI) system 100 is provided that may be configured, programmed, or otherwise utilized in accordance with the present disclosure. The MRI system 100 includes an operator workstation 102, which will typically include a display 104, one or more input devices 106 (such as a keyboard and mouse or the like), and a processor 108. The

processor **108** may include a commercially available programmable machine running a commercially available operating system. The operator workstation **102** provides the operator interface that enables scan prescriptions to be entered into the MRI system **100**. In general, the operator workstation **102** may be coupled to multiple servers, including a pulse sequence server **110**; a data acquisition server **112**; a data processing server **114**; and a data store server **116**. The operator workstation **102** and each server **110**, **112**, **114**, and **116** are connected to communicate with each other. For example, the servers **110**, **112**, **114**, and **116** may be connected via a communication system **140**, which may include any suitable network connection, whether wired, wireless, or a combination of both. As an example, the communication system **140** may include both proprietary or dedicated networks, as well as open networks, such as the internet.

[0035] The pulse sequence server **110** functions in response to instructions downloaded from the operator workstation **102** to operate a gradient system **118** and a radiofrequency (RF) system **120**. Gradient waveforms to perform the prescribed scan are produced and applied to the gradient system **118**, which excites gradient coils in an assembly **122** to produce the magnetic field gradients G_x , G_y , G_z used for position encoding magnetic resonance signals. The gradient coil assembly **122** forms part of a magnet assembly **124** that includes a polarizing magnet **126** and a whole-body RF coil **128**.

[0036] RF waveforms are applied by the RF system **120** to the RF coil **128**, or a separate local coil (not shown in FIG. 1), in order to perform the prescribed magnetic resonance pulse sequence. Responsive magnetic resonance signals detected by the RF coil **128**, or a separate local coil, are received by the RF system **120**, where they are amplified, demodulated, filtered, and digitized under direction of commands produced by the pulse sequence server **110**. The RF system **120** includes an RF transmitter for producing a wide variety of RF pulses used in MRI pulse sequences. The RF transmitter is responsive to the scan prescription and direction from the pulse sequence server **110** to produce RF pulses of the desired frequency, phase, and pulse amplitude waveform. The generated RF pulses may be applied to the whole-body RF coil **128** or to one or more local coils or coil arrays.

[0037] The RF system **120** also includes one or more RF receiver channels. Each RF receiver channel includes an RF preamplifier that amplifies the magnetic resonance signal received by the coil **128** to which it is connected, and a detector that detects and digitizes the I and Q quadrature components of the received magnetic resonance signal. The magnitude of the received magnetic resonance signal may, therefore, be determined at any sampled point by the square root of the sum of the squares of the I and Q components:

$$M = \sqrt{I^2 + Q^2}; \quad \text{Eqn. 1}$$

[0038] and the phase of the received magnetic resonance signal may also be determined according to the following relationship:

$$\varphi = \tan^{-1}\left(\frac{Q}{I}\right). \quad \text{Eqn. 2}$$

[0039] The pulse sequence server **110** also optionally receives patient data from a physiological acquisition controller **130**. By way of example, the physiological acquisition controller **130** may receive signals from a number of different sensors connected to the patient, such as electrocardiograph (ECG) signals from electrodes, or respiratory signals from a respiratory bellows or other respiratory monitoring device. Such signals are typically used by the pulse sequence server **110** to synchronize, or “gate,” the performance of the scan with the subject’s heartbeat or respiration.

[0040] The pulse sequence server **110** also connects to a scan room interface circuit **132** that receives signals from various sensors associated with the condition of the patient and the magnet system. It is also through the scan room interface circuit **132** that a patient positioning system **134** receives commands to move the patient to desired positions during the scan.

[0041] The digitized magnetic resonance signal samples produced by the RF system **120** are received by the data acquisition server **112**. The data acquisition server **112** operates in response to instructions downloaded from the operator workstation **102** to receive the real-time magnetic resonance data and provide buffer storage, such that no data are lost by data overrun. In some scans, the data acquisition server **112** does little more than pass the acquired magnetic resonance data to the data processor server **114**. However, in scans that require information derived from acquired magnetic resonance data to control the further performance of the scan, the data acquisition server **112** is programmed to produce such information and convey it to the pulse sequence server **110**. For example, during prescans, magnetic resonance data are acquired and used to calibrate the pulse sequence performed by the pulse sequence server **110**. As another example, navigator signals may be acquired and used to adjust the operating parameters of the RF system **120** or the gradient system **118**, or to control the view order in which k-space is sampled.

[0042] The data processing server **114** receives magnetic resonance data from the data acquisition server **112** and processes it in accordance with instructions downloaded from the operator workstation **102**. Such processing may, for example, include one or more of the following: reconstructing two-dimensional or three-dimensional images by performing a Fourier transformation of raw k-space data; performing other image reconstruction techniques, such as iterative or backprojection reconstruction techniques; applying filters to raw k-space data or to reconstructed images; generating functional magnetic resonance images; calculating motion or flow images; and so on.

[0043] Images reconstructed by the data processing server **114** are conveyed back to the operator workstation **102**. Images may be output to operator display **112** or a display **136** that is located near the magnet assembly **124** for use by attending clinician. Batch mode images or selected real time images are stored in a host database on disc storage **138**. When such images have been reconstructed and transferred to storage, the data processing server **114** notifies the data store server **116** on the operator workstation **102**. The

operator workstation **102** may be used by an operator to archive the images, produce films, or send the images via a network to other facilities.

[0044] The MRI system **100** may also include one or more networked workstations **142**. By way of example, a networked workstation **142** may include a display **144**, one or more input devices **146** (such as a keyboard and mouse or the like), and a processor **148**. The networked workstation **142** may be located within the same facility as the operator workstation **102**, or in a different facility, such as a different healthcare institution or clinic. The networked workstation **142** may include a mobile device, including phones or tablets.

[0045] The networked workstation **142**, whether within the same facility or in a different facility as the operator workstation **102**, may gain remote access to the data processing server **114** or data store server **116** via the communication system **140**. Accordingly, multiple networked workstations **142** may have access to the data processing server **114** and the data store server **116**. In this manner, magnetic resonance data, reconstructed images, or other data may be exchanged between the data processing server **114** or the data store server **116** and the networked workstations **142**, such that the data or images may be processed remotely by a networked workstation **142**. This data may be exchanged in any suitable format, such as in accordance with the transmission control protocol (TCP), the internet protocol (IP), or other known or suitable protocols.

[0046] The above-described MRI system of FIG. **1** can be used to implement a variety of pulse sequences to effectuate desired imaging studies. Furthermore, the systems and/or computers or processors described above can be programmed to carry out image or map reconstructions and/or derive a variety of clinically-desired metrics or measures. One category of pulse sequence is the gradient echo (GRE) sequence and variations thereof, such as spoiled gradient echo (SGRE) acquisitions. Referring to FIG. **2**, one non-limiting example of a pulse sequence **200** in accordance with the present disclosure is provided. In particular, the pulse sequence **200** of FIG. **2** is a GRE pulse sequence designed in accordance with the present disclosure. That is, as will be described, a multi-echo spoiled gradient echo pulse sequence can be used to provide simultaneous confounder-corrected estimation of PDFF and R_2^* values and/or a confidence map.

[0047] The pulse sequence **200** of FIG. **2** begins with a radio frequency (RF) pulse **202**, followed by slice and phase encoding achieved using respective slice-selective gradients **204**, **206** and phase-encoding gradients **208**, **210**. In particular, following excitation of the nuclear spins in the imaging slice prescribed by the slice encoding gradients **204**, **206**, phase encoding gradients **208**, **210** are applied to spatially encode the elicited echoes **212**. A series of readout gradients **214** are also applied starting with a dephasing gradient lobe **216** followed by the readout encoding **218** to spatially encode the echo **212** along a second, orthogonal direction in the prescribed imaging slice. Finally, a spoiler gradient **220** is applied. On selected passes or repetitions of the pulse sequence **200**, the pulses may be varied.

[0048] As described above, proton density fat-fraction (PDFF) and transverse relaxivity rate (R_2^*) acquired using a pulse sequence **200** such as described with respect to FIG. **2** to perform quantitative chemical shift-encoded MRI (CSE-MRI) studies are valuable biomarkers of diffuse liver

disease. For MR elastography in the liver region, several automated algorithms have been proposed. However, such analysis can be readily undermined by costly “call-backs” of the patient when the resulting data is unreliable.

[0049] That is, reliable PDFF and R_2^* quantification or estimation remains challenging due to confounding factors such as low SNR, high iron (high R_2^*), inhomogeneous magnetic field (B_0), and phase errors. In addition, water-fat swaps commonly occur in water- or fat-dominant pixels. Further, severe magnetic field inhomogeneities can lead to focally elevated and unreliable R_2^* and even PDFF estimates. Thus, a quantitative PDFF or R_2^* map may not clearly show the regions with inadequate or corrupted measurements, and there is a lack of guidance in current CSE-MRI methods, for objective identification of invalid regions of the maps.

[0050] Despite the plethora of compounding confounding or corrupting factors, the present disclosure is able to tell clinicians (or computerized analysis systems or algorithms) the amount of confidence that should be placed in a given measurement. As a non-limiting example, the systems and methods provided herein have identified a variety of scenarios that can lead to biased or incorrect values and provides systems and methods for communicating the amount of confidence that should be placed in a given value, even when multiple confounding or corrupting factors are present together compounding the obscurity of the measure.

[0051] As one non-limiting example, multiple scenarios have been identified that can lead to biased estimation or high variability of PDFF and/or R_2^* values. As some non-limiting examples, these scenarios can include (i) low SNR of underlying source images; (ii) moderate iron overload leading to invalid PDFF estimation, but valid R_2^* estimation; (iii) severe iron overload, leading to both invalid PDFF and R_2^* estimation; (iv) extraneous phase or amplitude errors in complex CSE-MRI methods; (v) water-fat/fat-water swapping; and/or (vi) tissues adjacent to areas of high susceptibility, such as metallic implants. Furthermore, as will be described, the present disclosure recognizes that PDFF and/or R_2^* measures in pixels suffering from bias or high variability can be excluded from subsequent analysis and reporting.

[0052] The present disclosure recognizes that PDFF and R_2^* measures exhibit increased variability and bias when SNR is low. CSE-MRI images have independent additive noise, resulting in variability in both signal magnitude and phase. Thus, whether using complex CSE-MRI data (magnitude and phase), magnitude only CSE-MRI data (discarding phase of the signal), or hybrid CSE-MRI data (a combination of complex and magnitude data or a combination of the resulting magnitude fitting and complex fitting), poor SNR in underlying echo images can lead to high variability and bias in PDFF and R_2^* maps. Noise does not propagate linearly in PDFF and R_2^* maps, making it difficult for experts to determine when SNR is sufficient.

[0053] The present disclosure further recognizes that signal decay caused by moderate iron overload worsens SNR in later echoes at higher echo time (TE) values. Though SNR may be adequate to estimate R_2^* reliably, water-fat separation and, therefore, PDFF estimation may be difficult. In the spectral domain, increasing R_2^* leads to line-width broadening and, when sufficiently severe, merges water and fat into an inseparably broad peak. More severe iron overload results in insufficient SNR to estimate either R_2^* and PDFF.

[0054] The present disclosure recognizes that phase or amplitude errors may be caused by a variety of sources, including eddy currents, concomitant gradients, or spurious phase or amplitude errors. Such phase or amplitude errors can lead to biased estimates of both PDFF and R_2^* . Successful strategies have been proposed to address eddy currents and concomitant gradients. However, it can be challenging to identify incompletely corrected or other spurious phase- or amplitude-related PDFF and R_2^* estimation errors. Phase and amplitude errors lead to anatomically accurate and visibly plausible PDFF and R_2^* maps, but with large quantitative errors not easily appreciated visually.

[0055] The present disclosure further recognizes that water-fat swapping occurs in regions with relatively high B_0 inhomogeneity, such as the liver dome. Swaps lead to bias in not only PDFF estimate, but also R_2^* because the spectral model of water (single-peak) and fat (multi-peak) are not the same. A pixel with a water-fat swap will inappropriately fit signal to the wrong spectral model, and the multi-peak interference of fat with itself will lead to an apparent under-(over-) estimation of R_2^* . Water-fat swaps are generally easy for expert human analysts to identify, although this is generally impractical to implement when using automated segmentation algorithms.

[0056] Further still, signal dephasing in tissue adjacent to sources of severe focal susceptibility, such as metallic implants and or abrupt tissue-air interfaces, can lead to over-estimation of R_2^* , and bias in PDFF.

[0057] In one, non-limiting example, a 6-peak model may be used to generate an estimate of PDFF and R_2^* from MR data acquired using a multi-echo spoiled gradient echo pulse sequence, such as described above with respect to FIG. 2.

[0058] In this context, multiple species of fat can be addressed as:

$$s(t) = \left(\rho_w + \rho_f \sum_{p=1}^6 \alpha_p \cdot e^{i2\pi f_p t} \right) \cdot e^{i2\pi \psi t}, \quad \text{Eqn. 3}$$

[0059] where ρ_w and ρ_f are the complex signal amplitude of water and fat components, α_p and f_p are relative amplitudes and frequencies for p^{th} peak of fat such that $\sum_{p=1}^6 \alpha_p = 1$, ψ is the “complex field map” that includes off-resonance frequency ψ_0 (Hz) and R_2^* (s^{-1}), defined as:

$$\psi = \psi_0 + \frac{iR_2^*}{2\pi}; \quad \text{Eqn. 4}$$

[0060] where PDFF is defined as:

$$\text{PDFF} = \frac{|\rho_f|}{|\rho_w| + |\rho_f|}. \quad \text{Eqn. 5}$$

[0061] PDFF and R_2^* can be estimated using iterative or non-linear estimation algorithms. Since this problem is non-convex, challenges such as inhomogeneous B_0 fields, low SNR, high R_2^* , and water-fat swaps, can result in inaccurate estimation of PDFF and/or R_2^* .

[0062] Inaccurate PDFF or R_2^* undercut the ability to use this information clinically. That is, in these situations, not only can the information be inaccurate, but there is no way

for the clinician to identify or determine and distinguish inaccurate information from accurate information. To overcome this problem, the present disclosure provides systems and methods to create confidence maps that identify inappropriate or inaccurate estimations of PDFF and R_2^* under a wide variety of scenarios, including all of those described above.

[0063] In one non-limiting example, to develop confidence maps, three classes can be identified. The first class can be defined by situations where poor SNR and/or phase (or amplitude) errors of the acquired signals are a potential source of inaccuracies. This first class can apply to all six scenarios above. The second class can be defined by a failure of B_0 estimation, which applies to the fifth scenario described above—water-fat swapping. The third class can be defined by an overestimation of R_2^* due to severe local susceptibility, which applies to the sixth scenario described above—tissues adjacent to areas of high susceptibility.

[0064] Using this construct, multiple confidence maps can be generated. For example, referring to FIG. 3, a process 300 for producing a confidence map in accordance with the present disclosure may produce multiple confidence maps, which may be delivered as a report and/or outputting individually or together.

[0065] Referring to FIG. 3, at a first stage 302, multiple source echo images are acquired. As used herein, acquiring multiple source echo images may include acquiring MR data from a subject, such as using the MRI system of FIG. 1 and a pulse sequence such as described with respect to FIG. 2. Alternatively, acquiring multiple source echo images may include accessing MR data or MR images stored on a computer system or in a memory of a computer system. Regardless of the source of the data or images, PDFF and R_2^* maps are reconstructed using a CSE-MRI algorithm with multi-peak signal modeling.

[0066] The first stage 304 can include multiple processing steps that can be performed in parallel or series. For example, at process block 306, masks ($C_{1,PDFF}$, $C_{1,R2^*}$) can be used to identify areas with poor quality of signals for PDFF and R_2^* measurements, which can be calculated based on the normalized root-mean-square error (NRMSE), Cramer-Rao Lower Bound, and Monte-Carlo simulation can provide confidence threshold of NRMSE.

[0067] More particularly, the first mask can identify areas with poor quality signals for estimation of $C_{1,PDFF}$ and $C_{1,R2^*}$. Confidence maps can be based on the NRMSE between the measured signal and CSE-MRI signal model, in the least-squares sense (i.e., L2 norm). Any NRMSE value above a pre-determined threshold criteria may be utilized. A process for determining the threshold using Cramér-Rao Lower Bound (CRLB) and Monte-Carlo analyses will be described below.

[0068] At process block 308, the NRMSE for signal fitting with and without off-resonance shifts (± 3.4 ppm) can be compared to detect water-fat swapping (C_2). That is, the NRMSE can also be used to assess water-fat swaps generated using forced water-fat swaps, by comparing each fit with signal models that have off-resonance frequencies to enforce a water-fat swap, and estimating the probability of a water-fat swap. Note that PDFF and R_2^* can share the same mask for water-fat swaps, hence $C_2(r) = C_{2,PDFF}(r) = C_{2,R2^*}(r)$.

[0069] Furthermore, at process block 310, to exclude areas with strong R_2^* decay due to susceptibility effect, suscep-

tibility effect masks ($C_{3,PDFF}$ and $C_{3,R2^*}$) can be calculated based on the local B_0 gradient. For example, severe local susceptibility caused by metallic implants or air-tissue interfaces, can be evaluated using the local spatial gradient of the B_0 inhomogeneity (ψ_0) to generate $C_{3,PDFF}$ and $C_{3,R2^*}$.

[0070] Finally, in addition to these specific confidence map focused on scenarios i-iv produced at process block 306, the confidence map focused on scenario v produced at process block 308, and/or the confidence map focused on scenario vi produced at process block 310, overall confidence maps for PDFF and R_2^* can be derived by using the binary AND 312 combination of C_1 , C_2 , and C_3 . As one non-limiting example, the overall confidence maps for PDFF and R_2^* can be determined through the binary AND operation as:

$$C_{PDFF}(r) = C_{1,PDFF}(r) \wedge C_2(r) \wedge C_{3,PDFF}(r) \quad \text{Eqn. (6)}$$

$$C_{R2^*}(r) = C_{1,R2^*}(r) \wedge C_2(r) \wedge C_{3,R2^*}(r);$$

[0071] where \wedge represents the AND operator and noting that $C_2(r) = C_{2,PDFF}(r) = C_{2,R2^*}(r)$ for water-fat swaps. The resulting confidence maps for PDFF and R_2^* maps indicate areas with high and low reliability for ROI-based analysis. Thus, as illustrated, multiple classes of confidence maps can be generated, as illustrated at 314. Therefore, the systems and methods provided herein can produce confidence map(s) for PDFF and R_2^* maps generated using CSE-MRI. Confidence maps can be based on NRMSE values, in combination with masking for the presence of water-fat swaps and areas of high local magnetic susceptibility.

[0072] At process block 316, the system or algorithm may create any of a variety of outputs. For example, the confidence maps may be individually compiled to generate a report. Additionally or alternatively, the confidence maps may be combined. Additionally or alternatively, the confidence maps may be output to a reconstruction process for the quantitative maps, which may include elastograms.

[0073] The systems and methods provided herein can be used to predict the presence of water-fat swaps and this information may be incorporated into the PDFF and R_2^* map reconstruction, which can obviate the need to mask regions of water-fat swaps. Additionally or alternatively, the confidence maps may be incorporated into an automated map production or analysis system, such as to supplement or supplant expert analysis, such as described below.

Evaluation for Quality of Acquired Signal

[0074] The reliability of PDFF and R_2^* estimates can be evaluated using the NRMSE between the measured and fitted signals and non-linear least squares estimation. This method evaluates the agreement between the measured and modeled complex signal, defined as:

$$NRMSE = \frac{1}{\hat{y}} \sqrt{\sum_{n=1}^N \frac{(y_n - \hat{y}_n)^2}{N}}; \quad \text{Eqn. (7)}$$

[0075] where y_n and \hat{y}_n are the measured and estimated complex signals at n^{th} echo and \hat{y} is the mean value of

the measured signals. NRMSE is a convenient metric to provide a confidence threshold, defined as:

$$C_1(r) = \begin{cases} 1 & \text{if } NRMSE(r) \leq \tau; \\ 0 & \text{if } NRMSE(r) > \tau; \end{cases} \quad \text{Eqn. (8)}$$

[0076] where r is the spatial coordinate of the map and τ is a predetermined threshold value, above which the signals from voxel at position r do not adequately fit the signal model to be considered reliable.

[0077] The threshold τ can vary with PDFF and R_2^* , as well as pulse sequence parameters, most notably first echo time (TE_1), echo spacing (ΔTE) and echo train length. In one configuration, the values of τ was studied as a function of PDFF, R_2^* , TE_1 , and ΔTE using the CRLB and Monte-Carlo simulations, as described below, for a fixed echo train length of six.

Detection of Water-Fat Swapping

[0078] Water-fat swapping is a well-known challenge with CSE-MRI caused by incorrect estimation of the B_0 field map resulting from fitting to a local minimum, particularly in water- or fat-dominant pixels. Swaps are commonly seen in the liver dome but can occur anywhere. Since swapping leads to highly biased estimates of both PDFF and R_2^* , it can be important to exclude these regions.

[0079] Water-fat swapping often occurs two ways with CSE-MRI. For PDFF values below 50%, when a swap occurs, the estimated field map (ψ_0) is estimated at +3.4 ppm higher than the true B_0 field, corresponding to the methylene peak of fat. This results in overestimation of PDFF, and is common with typical PDFF values observed in the liver. When PDFF exceeds 50% and a swap occurs, the estimated field map is underestimated by -3.4 ppm, which corresponds to the water peak, and PDFF is underestimated.

[0080] That is, referring to FIGS. 4A-4D, there are two general scenarios that cause water-fat swapping with multi-peak signal modeling. Referring to FIG. 4A, for PDFF < 50%, the estimated off-resonance frequency is overestimated, when with a water-fat swap caused by an error in B_0 estimation, as shown in FIG. 4B. Referring to FIG. 4C, for PDFF > 50%, off-resonance and PDFF is underestimated, with a water-fat swap, as show in in FIG. 4D. The over- or under-estimation of off-resonance leads to an increased NRMSE since a residual component of fitting remains, since the spectral models of water (single peak) and fat (multi-peak) are different.

[0081] When swaps occur, the agreement between measured and fitted signals decreases, due to differences in the spectral model of water (single peak) and fat (multi-peak), leading to an increase in the NRMSE. A swap can be enforced by fitting the signal with a shift of +3.4, -3.4 ppm relative to the estimated frequency, by substituting the frequency term as:

$$\psi_0 \leftarrow \psi_0 + \Delta\psi; \quad \text{Eqn. (9)}$$

[0082] where $\Delta\psi$ is the off-resonance shift corresponding to ± 3.4 ppm (e.g., ± 217 Hz at 1.5T). Calculating NRMSE values for each fitted signals can be used to predict the presence of a swap. Since the fitting with

lower NRMSE should be correct, the confidence map which is reflecting swapping can be defined as:

$$C_2(r) = \begin{cases} 1 & \text{if } \text{NRMSE}(r) \leq \text{NRMSE}_{\Delta\psi=\pm 3.4}(r) \\ 0 & \text{if } \text{NRMSE}(r) > \text{NRMSE}_{\Delta\psi=\pm 3.4}(r) \end{cases}; \quad \text{Eqn. (10)}$$

[0083] where $\text{NRMSE}_{\Delta\psi=\pm 3.4}$ is NRMSE for the fitted signal with the off-resonance shift. This principle has been proposed to exploit the spectral complexity of fat to mitigate fat-water swaps.

Detection of Focal Susceptibility Gradients

[0084] Strong local off-resonance due to sources of susceptibility such as metallic implants or tissue-air interfaces, accelerates signal decay and lead to local over-estimation of the apparent R_2^* . The B_0 field gradient in the largest voxel dimension (usually slice) can be used to exclude regions of high susceptibility by using gradient threshold κ as:

$$C_{3,R2^*}(r) = \begin{cases} 1 & \text{if } \Delta \cdot G > \kappa \\ 0 & \text{if } \Delta \cdot G \leq \kappa \end{cases}; \quad \text{Eqn. (11)}$$

[0085] with

$$G \equiv \frac{\partial}{\partial z}(\psi_0); \quad \text{Eqn. (12)}$$

[0086] where ψ_0 is the estimated B_0 map from equation (4), Δ denotes the largest voxel dimension (e.g., slice direction), and z is the coordinate system in that direction. The B_0 map can also be approximated from the phase difference of any two or more echo images if B_0 estimation from CSE-MRI is unreliable due to rapid signal decay (e.g., severe R_2^*). The echo images should be selected such that the phase of water and fat signals are similar, to prevent estimation errors caused by differences in off-resonance between water and fat. Gradient thresholds, κ , can be chosen based on numerical simulations of R_2^* decay with B_0 field gradients.

[0087] Specifically, Bloch equation simulations of signal decay due to B_0 field gradients using a point spread function approach can be used to estimate κ for equation (11). Assuming a rectangular slice profile, the additional R_2^* decay due to the macroscopic B_0 field gradients in a specific direction can be expressed by:

$$s(t, G) = \left(\rho_w + \rho_f \sum_{p=1}^P \alpha_p \cdot e^{j2\pi f_p t} \right) \cdot e^{j2\pi\psi(z)t} \cdot \Delta \cdot \text{sinc}(\gamma \cdot \Delta \cdot G \cdot t); \quad \text{Eqn. (13)}$$

[0088] where G is the field gradient defined in equation (12). A field gradient can be assumed along the largest voxel dimension, which is typically the slice direction with CSE-MRI in the liver. Although these assumptions may not be entirely accurate for 3D acquisitions, the proposed method provides practical criteria.

[0089] That is, the algorithm was validated for detecting focal susceptibility gradients using a case involving metal implant artifacts. R_2^* and field gradient (ΔG) in the left lobe, which is close to the implant artifacts, were measured in a

ROI. In this analysis, R_2^* measurement bias (ΔR_2^*) was calculated pixel-pixel by subtracting the mean R_2^* (32.6 1/s) in the right lobe from the measured R_2^* . A scatter plot of ΔR_2^* against ΔG showed that measurement bias tended to increase as ΔG increases, especially above 20 Hz. For the mean R_2^* , the algorithm predicted 8.3 Hz, which provides reasonable criteria for measurement, although it is a conservative number.

[0090] Although an assumption of ideal slice profile and field gradient along only slice direction may be used, the results indicated that the result was sufficient. To obtain more accurate threshold value, the three-dimensional distribution of field gradient and realistic spatial response function of 3D imaging can be used.

[0091] The apparent R_2^* , which includes the effects of the B_0 gradient, can be calculated from the full width half maximum (FWHM) of frequency domain of the signal as:

$$R2^{*+}(\Delta \cdot G) = \frac{1}{\pi \cdot \text{FWHM}(\Delta \cdot G)}; \quad \text{Eqn. (14)}$$

[0092] such that the bias of $R2^*$ estimation ($\Delta R2^*$) is defined as:

$$\Delta R2^*(\Delta \cdot G) = R2^{*+}(\Delta \cdot G) - R2^*; \quad \text{Eqn. (15)}$$

[0093] Threshold criteria (κ) can be chosen such that the bias on R_2^* estimates are within a desired range such that:

$$\kappa = \arg \min_G |\Delta R2^*(\Delta \cdot G) - R2^*|; \quad \text{Eqn. (16)}$$

[0094] where $R2^*_{\text{T}}$ is the maximum acceptable R_2^* bias.

[0095] PDFF estimates can also be affected by B_0 gradients, although generally less so than R_2^* . Mild field gradients still allow for accurate estimation because they broaden the water and fat spectra, which manifests as an R_2^* overestimation, leaving PDFF relatively unaffected. When the field gradient reaches a sufficient amplitude, the spectra become highly broadened, leading to complicated signal decay, and failure of PDFF estimation.

[0096] Therefore, the susceptibility effect map for PDFF can be defined as:

$$C_{3,PDFF}(r) = \begin{cases} 1 & \text{if } \Delta \cdot G > \kappa' \\ 0 & \text{if } \Delta \cdot G \leq \kappa' \end{cases}; \quad \text{Eqn. (17)}$$

[0097] where G_c is cutoff gradient value that allows acceptable bias. In this study, values for κ' of 51 Hz and 93 Hz for 1.5T and 3.0T were used, respectively. These values were determined using Monte-Carlo simulations.

Cramér-Rao Lower Bound (CRLB) and Monte-Carlo (MC) Simulation

[0098] CRLB and MC simulations can be used to determine NRMSE thresholds in two steps. First, the minimum

SNR necessary to meet the target variability (as characterized by the standard deviation of PDFF and R_2^*) can be determined by using CRLB. MC and nonlinear regression analyses can then be used to obtain regression models that establish the relationship between SNR and NRMSE. These analyses provide the relationship between NRMSE and standard deviation, indirectly, and assumes that the estimators of PDFF and R_2^* are efficient, which is generally the case for most CSE-MRI methods.

[0099] The CRLB, derived from the signal model, such as equation (3) for CSE-MRI, provides a theoretical lower bound on the variance of any unbiased estimator for PDFF ($\text{CRLB}_{\text{PDFF}}$) and R_2^* ($\text{CRLB}_{R_2^*}$) estimated for a specific combination of PDFF, R_2^* , TE_1 , ΔTE , and SNR, assuming a fixed echo train length.

[0100] Using ROI analysis, analysts typically estimate the mean of the estimated values from a region of tissue, with Z independent samples. The minimum SNR is chosen such that standard error (SE) of the mean of the estimated PDFF or R_2^* value is below an acceptable variance threshold. In this work, SE is defined as:

$$SE = \frac{\sigma}{\sqrt{Z}}; \quad \text{Eqn. (18)}$$

[0101] where σ is a standard deviation of PDFF or R_2^* , and Z is the number of independent samples in an ROI. Threshold criteria for variability in PDFF and R_2^* estimates, and Z will vary depending on specific applications. The minimum SNR values needed to achieve reliable estimates are obtained by solving the following minimization problems,

$$\begin{aligned} \text{SNR}_{\text{PDFF}}(x) &= \underset{\text{SNR}}{\text{argmin}} \left| \frac{\text{CRLB}_{\text{PDFF}}(\text{SNR}, x)}{\sqrt{Z}} - SE_{\text{PDFF}} \right| \\ \text{SNR}_{R_2^*}(x) &= \underset{\text{SNR}}{\text{argmin}} \left| \frac{\text{CRLB}_{R_2^*}(\text{SNR}, x)}{\sqrt{Z}} - SE_{R_2^*} \right| \end{aligned} \quad \text{Eqn. (19)}$$

[0102] with

$$x = (\text{PDFF}, R_2^*, TE_1, \Delta TE); \quad \text{Eqn. (20)}$$

[0103] where $\text{CRLB}_{\text{PDFF}}$ and $\text{CRLB}_{R_2^*}$ are the minimum standard deviation, calculated from CRLB analysis for PDFF and R_2^* , respectively; SE_{PDFF} and $SE_{R_2^*}$ are acceptable SE for PDFF and R_2^* , respectively. SNR_{PDFF} and $\text{SNR}_{R_2^*}$ are calculated over a range of plausible TE_1 , ΔTE , PDFF, and R_2^* values.

[0104] Because accurate SNR measurements can be a challenge, in general, an approach to estimate SNR from NRMSE can be used. To determine the relationship between NRMSE and SNR, MC simulations can be performed with variable PDFF, R_2^* , TE_1 , ΔTE , and SNR values, and repeated Z times for each set of parameters to replicate measurements within a region of interest (ROI) containing Z pixels, simulating an ROI measurement from a PDFF or R_2^* map. Mean NRMSE and SNR values were measured from the repeated calculations and plotted. An empirical function $F(\text{SNR})$ representing the NRMSE for a specific SNR value

can be obtained by fitting the curves, for example, with a neural network regression model.

[0105] Using this relationship, thresholds of NRMSE for PDFF and R_2^* can be estimated by combining the obtained two regressions as:

$$\begin{aligned} \tau_{\text{PDFF}}(x) &= F(\text{SNR}_{\text{PDFF}}(x)); \\ \tau_{R_2^*}(x) &= F(\text{SNR}_{R_2^*}(x)); \end{aligned} \quad \text{Eqn. (21)}$$

[0106] where τ_{PDFF} and $\tau_{R_2^*}$ are the thresholds used in equation 6 to determine the reliability of PDFF and R_2^* measurements.

EXPERIMENTS

[0107] Thus, as described above, a system and method are provided to provide confidence maps. To evaluate the performance of the confidence map algorithm, MC simulations, phantom, and in vivo experiments were performed. The generation of the quantitative PDFF and R_2^* maps used for the confidence maps was performed offline using the ISMRM Fat-Water toolbox. Water and fat images, and PDFF and R_2^* maps were reconstructed from complex images using a nonlinear least-squares estimation method. Confidence maps for PDFF and R_2^* were independently generated pixel-by-pixel using the equation (6), and final PDFF and R_2^* maps with confidence map overlays were exported as DICOM images for phantom and in vivo experiments.

Confidence Map

[0108] A broad physiologically plausible range of R_2^* and PDFF were used, along with broad but plausible ranges for TE_1 , ΔTE , SNR, and off-resonance frequency. The range for PDFF and was chosen from 0-100%, and the range for R_2^* was 25-500 s^{-1} at 1.5T and 25-1000 s^{-1} at 3.0T, respectively, based on previous studies. The ranges of TE_1 (0.9-1.8 and 0.6-1.0 ms for 1.5T and 3.0T, respectively) and ΔTE (1.1-2.2 and 0.55-1.1 ms for 1.5T and 3.0T, respectively) were based on that typically allowed by vendors, and past optimizations. Off-resonance frequencies of -14.5-81.3 Hz and -31.7-164.0 Hz for 1.5T and 3.0T, respectively were used based on the known variability of B_0 in the liver. SNR of the first echo was varied between 2-50. An echo train length of 6 was chosen, as this value is widely used for clinical CSE-MRI acquisitions.

[0109] Criteria for reliable measurements of PDFF and R_2^* were determined based on previous clinical studies. Specifically, the coefficients of repeatability for PDFF and R_2^* in the liver were investigated based on prior in-vivo studies. It has reported that PDFF measurement using CSE-MRI showed repeatability coefficients of 2.99%, respectively. For R_2^* , it has been reported that the test-retest R_2^* repeatability using Bland-Altman analysis at both 1.5T (95% limit of agreement (LOA): -14.2-16.9%, Bias: 1.4%) and 3.0T (95% LOA: -16.6-15.5%, Bias: -0.6%) as part of a multi-center, multi-vendor study.

[0110] Based on these results, the thresholds were chosen to lead to standard error (SE) values much less than these coefficients of repeatability to avoid impacting the test-retest variability of CSE-MRI. Specifically, the selections were made to achieve a SE of 1% (absolute) or less for PDFF, and less than 3% (relative) or 5 s^{-1} (whichever is larger) for R_2^* . A circular ROI was assumed with 2.8 cm diameter, corre-

sponding to 100 pixels for in-plane spatial resolution of $2.0 \times 3.0 \text{ mm}^2$, typical for CSE-MRI.

Simulation Experiments

[0111] Monte-Carlo (MC) simulations using signal generated with the model in equation (3) were performed (MATLAB 2021b) to evaluate the performance of the proposed confidence map algorithm. The same ranges of parameters for R_2^* , PDFF, TE_1 , ΔTE , SNR, and off-resonance frequency as those assumed for the confidence map were applied. Zero-mean complex Gaussian noise was added to the simulated signal to vary SNR. The variance of the estimated values of PDFF and R_2^* for a particular NRMSE was calculated using a binned scatterplot.

[0112] Additional MC simulations were used to evaluate the performance of the proposed water-fat swap detection method using the same parameter range explained above. We implemented the algorithm in equation (8) and plotted probabilities that successfully detected swapping against NRMSE for 1.5T and 3.0T.

[0113] To obtain an empirical relationship between SNR_{PDFF} and $SNR_{R_2^*}$ with NRMSE, the results from equation (19) were fit to a shallow neural network regression model consisting of three fully connected hidden layers with 10 neurons using the fitnet function provided in MATLAB. The same model was used for fitting F, which showed the relationship between NRMSE and SNR.

[0114] R_2^* bias due to macroscopic B_0 inhomogeneity was calculated with variable R_2^* ($25\text{-}1000 \text{ s}^{-1}$) and B_0 using equations (13)-(15). An empirical relationship between the B_0 gradient and R_2^* was developed to determine the threshold κ in equation (11), obtained by fitting the calculated results to polynomial regression model up to 3rd order, followed by the application of equation (16).

Phantom Experiments

[0115] Phantom experiments were performed to validate the performance of the confidence map algorithm. A prototype phantom (Calimetrix, Madison, WI) consisting of 16 vials with simultaneously varying PDFF and R_2^* enclosed within a spherical housing unit was used. PDFF and R_2^* maps were acquired using a 3.0T clinical MR system (Signa Premier, GE Healthcare, Waukesha, WI). Acquisition parameters are summarized in Table 1.

[0116] To obtain low SNR images, a flip angle of 1° was used. An increasing number of signal averages (NSA) from 1-9 was used to vary SNR. To perform quantitative analysis, PDFF and R_2^* values were measured. ROIs were placed in each vial to perform a box plot analysis. The above-described systems and methods for creating confidence maps were applied to the acquired maps.

In Vivo Experiments

[0117] A prospective clinical study was performed by performing a retrospective analysis of CSE-MRI data collected from consecutive patients undergoing PDFF and R_2^* measurements in the liver as part of clinical MR exams. Imaging for the subjects was implemented using various 1.5T and 3.0T clinical MR systems (GE Healthcare, Waukesha, WI). A commercial CSE-MRI method (IDEAL-IQ GE Healthcare, Waukesha, WI) with imaging parameters listed in Table 1 was used.

[0118] A board-certified radiologist delineated ROIs for each of 9 liver segments blinded to the confidence maps. The percent area of the ROIs was then calculated in areas that were identified by the confidence map as invalid. In this way, we aimed to determine the impact of confidence maps on clinical analysis, since those areas would have been avoided if the confidence maps had been made available to the radiologist or an automated segmentation algorithm.

Results

[0119] Referring to FIGS. 5A and 5B, plots are provided that are a function of NRMSE and R_2^* for R_2^* and PDFF calculated using MC simulations with 1.5T and 3.0T, respectively. Threshold values calculated using the above-described systems and methods (white solid lines) agree with estimates from MC simulations (dotted line). The plots also demonstrate that threshold values are moderately dependent on R_2^* but less dependent on PDFF.

[0120] MC simulations reveal water-fat swapping can be successfully detected using the proposed method for wide range of PDFF and R_2^* values. FIGS. 6A and 6B show the probability of water-fat swapping as a function of PDFF and R_2^* for 1.5T (FIG. 6A) and 3.0T (FIG. 6B).

[0121] The above-described systems and methods can detect swapping with, in this limited context, 80% probabil-

TABLE 1

	Phantom	In vivo	
	3.0T	1.5T	3.0T
TR	6.2 ms	8.3-13.6 ms	4.9-7.5 ms
TE_1	1.0 ms	0.9-1.7 ms	0.9-1.0 ms
ΔTE	0.7 ms	1.8-2.1 ms	0.59-1.0 ms
# Echoes	3	3	3
# Interleaved Echo Trains	2	2	2
Receiver Bandwidth	781 Hz/px	651 Hz/px	781 Hz/px
FOV	40 cm	40-46 cm	36-40 cm
Slice Thickness	2 mm	7.8-10 mm	8-10 mm
Number of slices	20	56-72	28-36
Matrix Size	160×160	$184 \times 112\text{-}192 \times 160$	$116 \times 104\text{-}192 \times 160$
Flip Angle	1	5°	$3\text{-}4^\circ$
NSA	1, 9	0.5	0.5

ity for most PDFF and R_2^* values. The probability of a water-fat swap detection drops dramatically at high R_2^* , as expected.

[0122] FIGS. 7A-7C are plots of the estimation bias in % associated with low- ($50\text{--}100\text{ s}^{-1}$), mid- ($100\text{--}300\text{ s}^{-1}$), and high- R_2^* ($300\text{--}1000\text{ s}^{-1}$) due to B_0 inhomogeneities. There is a strong relationship between estimation bias and B_0 gradient and R_2^* . A relatively small B_0 gradient will lead to some bias at low R_2^* values, whereas high R_2^* values are less biased. Based on these results, threshold values for B_0 gradients are shown as the white dotted lines in FIGS. 7A-7C, for use with equation (16).

[0123] Data from the phantom experiments demonstrated that the systems and methods provided herein identified areas not suitable for PDFF and R_2^* measurements under various SNR conditions. The PDFF and R_2^* maps obtained with high SNR (NSA=9) had appropriate SE values for PDFF and R_2^* measurements. Similarly, the systems and methods described herein identified regions with poor SE in PDFF and R_2^* for the low SNR acquisition (NSA=1). ROIs in vials 4, 8, 12, and 16 in the PDFF map acquired with NSA=1 were excluded as unreliable PDFF (SE=1.1%, 1.7%, 0.79%, 0.71%). The systems and methods also identified most of vials 8 and 16 as invalid for analysis (SE=3.7%, 2.4%). The box plots of FIG. 8 show how these ROIs have relatively high PDFF and/or R_2^* variability.

[0124] Raw data from 100 consecutive patients (1.5T: 51, 3.0T: 49 patients, 51:49 men:women, 56 range: 18-82 years) who underwent CSE-MRI of the liver as part of their clinical MR exam was successfully collected and reconstructed as described above. PDFF and R_2^* maps with high R_2^* ($>500\text{ s}^{-1}$), as well as histograms with PDFF and R_2^* values from ROIs located in the right lobe, demonstrated that the systems and methods provided herein successfully identified unreliable regions. A measurement of this example indicated unacceptable variability (SE=1.7%) in PDFF maps, while R_2^* (SE=2.3%) was within the defined criteria. A metal implant in the abdominal wall caused severe susceptibility artifacts in both PDFF and R_2^* maps and was properly identified using the systems and methods provided herein. Most fatty regions in R_2^* were masked out because the B_0 field gradient was above the defined threshold (κ), which was caused by interface between fat and water tissues. These regions were successfully masked using the confidence maps.

[0125] In total, 832 ROIs were placed by the radiologist, with 68 ROIs not placed due to poor image quality, such as motion artifacts. ROI analysis by the radiologist revealed that 2.6% and 15% of the area of the ROIs in PDFF and R_2^* maps were placed inside unreliable areas identified by confidence maps. Notably, 5.4% and 49% of ROIs for PDFF and R_2^* maps, respectively, had more than 10% of invalid pixels. Further, there were significant differences in PDFF ($4.3\%\pm 4.4\%$) and R_2^* ($18.7\text{ s}^{-1}\pm 34\text{ s}^{-1}$) measurements with and without confidence maps in 1% and 12% of the cases, respectively. Twenty-six cases had water-fat swapping, and two had severe focal metal artifacts, respectively. Furthermore, three cases had unreliable PDFF due to moderate levels of R_2^* , while R_2^* estimates were acceptable. No cases with extreme R_2^* values were seen.

[0126] Thus, the systems and methods described herein were validated in both in vitro and in vivo settings and generated confidence maps for PDFF and R_2^* maps measured in the liver using CSE-MRI. Confidence maps were

generated based on NRMSE values between the signal model and measured signals. Further, areas of water-fat swapping and regions of severe susceptibility artifact from metal were excluded. Monte-Carlo simulations, a phantom study and clinical study demonstrated the validity and utility of the proposed algorithm.

[0127] The systems and methods described herein can generate confidence maps as an output and/or can be part of an automated system and method to identify reliable and unreliable regions of PDFF and R_2^* maps. Such maps are clinically valuable because they provide clinicians with accurate and precise estimates of PDFF and R_2^* needed to diagnose, stage, and monitor treatment of patients with, for example, liver disease. The systems and methods provided herein can be used to avoid inappropriate ROI placement by analysts and can improve the quality and consistency of PDFF and R_2^* measurements.

[0128] The systems and methods provided herein can be used for a variety of CSE-MRI applications. That is, the experiments provided above were applied in the clinical context of liver imaging. However, the systems and methods provided herein are not limited to this clinical setting or liver imaging. The threshold values may vary depending on specific applications. However, the systems and methods provided herein can be applied to any CSE-MRI measurement by changing simply adjusting threshold used to generate the confidence maps.

[0129] As described above, invalid regions of R_2^* and/or PDFF estimation can be relatively common. Furthermore, focal severe susceptibility artifacts can occur with non-negligible frequency. It is important to note that, although the expert radiologist can exclude inappropriate areas in many cases, confidence maps are important aids for non-expert analysts, and necessary for fully automated tools.

[0130] The present disclosure recognizes that several estimation algorithms exist for PDFF and R_2^* . It may be desirable to adjust the threshold used for the confidence map for a given algorithm.

[0131] In some implementations, devices or systems disclosed herein can be utilized or installed using methods embodying aspects of the invention. Correspondingly, description herein of particular features or capabilities of a device or system is generally intended to include disclosure of a method of using such features for intended purposes and of implementing such capabilities. Similarly, express discussion of any method of using a particular device or system, unless otherwise indicated or limited, is intended to inherently include disclosure, as embodiments of the invention, of the utilized features and implemented capabilities of such device or system.

[0132] As used herein, unless otherwise limited or defined, “or” indicates a non-exclusive list of components or operations that can be present in any variety of combinations, rather than an exclusive list of components that can be present only as alternatives to each other. For example, a list of “A, B, or C” indicates options of: A; B; C; A and B; A and C; B and C; and A, B, and C. Correspondingly, the term “or” as used herein is intended to indicate exclusive alternatives only when preceded by terms of exclusivity, such as “only one of,” or “exactly one of.” For example, a list of “only one of A, B, or C” indicates options of: A, but not B and C; B, but not A and C; and C, but not A and B. In contrast, a list preceded by “one or more” (and variations thereon) and including “or” to separate listed elements indicates options

of one or more of any or all of the listed elements. For example, the phrases “one or more of A, B, or C” and “at least one of A, B, or C” indicate options of: one or more A; one or more B; one or more C; one or more A and one or more B; one or more B and one or more C; one or more A and one or more C; and one or more A, one or more B, and one or more C. Similarly, a list preceded by “a plurality of” (and variations thereon) and including “or” to separate listed elements indicates options of one or more of each of multiple of the listed elements. For example, the phrases “a plurality of A, B, or C” and “two or more of A, B, or C” indicate options of: one or more A and one or more B; one or more B and one or more C; one or more A and one or more C; and one or more A, one or more B, and one or more C.

[0133] The present invention has been described in terms of one or more preferred embodiments, and it should be appreciated that many equivalents, alternatives, variations, and modifications, aside from those expressly stated, are possible and within the scope of the invention.

1. A magnetic resonance imaging (MRI) system comprising:

- a magnet system configured to generate a static magnetic field (B_0) about at least a portion of a subject arranged in the MRI system;
- a plurality of gradient coils configured to apply magnetic gradients to the polarizing magnetic field;
- a radio frequency (RF) system configured to apply an excitation field to the subject;
- a computer system programmed to:
 - control the plurality of gradient coils and the RF system to perform a multi-echo gradient echo pulse sequence to acquire chemical-shift encoded magnetic resonance (MR) data from a region of interest (ROI) in the subject;
 - estimate at least one of proton density fat fraction (PDFF) or R_2^* in the ROI using the MR data;
 - generate at least one confidence map that indicates an accuracy of the estimate of the at least one of the PDFF or R_2^* in the ROI; and
- a display to display one of (i) the at least one confidence map or (ii) a PDFF or R_2^* map corrected using the at least one confidence map.

2. The MRI system of claim 1, wherein the computer system is further programmed to evaluate the estimate of the at least one of the PDFF or R_2^* in the ROI using a threshold.

3. The MRI system of claim 2, wherein the threshold includes a normalized root-mean-square-error (NRMSE) threshold.

4. The MRI system of claim 1, wherein the computer system is further programmed to identify water-fat swapping in the MR data by performing a set of calculations of water-fat separation with fixed off-resonance shifts.

5. The MRI system of claim 4, wherein the fixed off-resonance shifts include +3.4 ppm and -3.4 ppm relative to an estimated frequency.

6. The MRI system of claim 1, wherein the computer system is further programmed to analyze the MR data to detect R_2^* decay caused by local magnetic field variations.

7. The MRI system of claim 1, wherein the computer system is further configured to generate multiple confidence maps using multiple processing stages and combine the multiple confidence maps into an overall confidence map.

8. A method for generating at least one confidence map indicating the accuracy of a quantitative map generated from magnetic resonance (MR) data acquired from a subject, the method comprising:

accessing, using a computer system, at least one of a proton density fat fraction (PDFF) map or R_2^* map produced from the MR data;

processing, using the computer system, the at least one of the PDFF map or R_2^* map using a threshold to identify spatial locations in the PDFF map or R_2^* map with at least one of poor quality of signals for PDFF or R_2^* measurements or water-fat swaps; and

communicating, using the computer system, a report including at least one of (i) the spatial locations with poor quality of signals for PDFF or R_2^* measurements or water-fat swaps or (ii) a PDFF or R_2^* map corrected using the spatial locations with poor quality of signals for PDFF or R_2^* measurements or water-fat swaps.

9. The method of claim 8, further comprising, using the computer system, identifying spatial locations with strong R_2^* decay due to susceptibility effects and indicating the spatial locations with strong R_2^* decay due to susceptibility effects in the report or using the spatial locations with strong R_2^* decay due to susceptibility effects to correct the PDFF or R_2^* map.

10. The method of claim 8, further comprising, using the computer system to identify water-fat swapping by performing a set of calculations of water-fat separation with fixed off-resonance shifts.

11. The method of claim 10, wherein the fixed off-resonance shifts include at least +3.4 ppm and -3.4 ppm relative to an estimated frequency.

12. The method of claim 8, further comprising, using the computer system, generating a confidence map for each step of a multi-stage process of:

- (a) spatial locations in the PDFF map or R_2^* map with at least one of poor quality of signals for PDFF or R_2^* measurements;
- (b) spatial locations in the PDFF map or R_2^* map that are subject to water-fat swaps; and
- (c) spatial locations with strong R_2^* decay due to susceptibility effects.

13. The method of claim 12, further comprising, using the computer system, combining each confidence map of steps (a) through (c) into an overall confidence map.

14. The method of claim 8, further comprising, using the computer system, at least one of:

- displaying the report;
- using the report to reconstruct a corrected PDFF or R_2^* map; or
- using the report in an automated map production or analysis system.

15. A non-transitory, computer-readable storage medium having stored thereon instructions that, when executed by a computer processor, causes the computer processor to carry out steps comprising:

accessing at least one of proton density fat fraction (PDFF) or R_2^* maps of a region of interest (ROI) of a subject produced using chemical-shift encoded magnetic resonance (MR) data acquired from the ROI in the subject;

generating at least one confidence map that indicates an accuracy of the at least one of the PDFF or R_2^* maps; and

outputting at least one of (i) the at least one confidence map or (ii) a corrected PDFF or R_2^* map that is corrected using the at least one confidence map.

16. The storage medium of claim **15**, further comprising generating the at least one confidence map using a multi-stage process including steps comprising:

identifying spatial locations in the at least one PDFF or R_2^* maps with at least one of poor quality of signals for PDFF or R_2^* measurements;

identifying spatial locations in the at least one of PDFF or R_2^* maps for water-fat swaps; and

identifying spatial locations in the at least one of PDFF or R_2^* maps for strong R_2^* decay due to susceptibility effects.

17. The storage medium of claim **16**, further comprising generating a confidence map for each step of the multi-stage process.

18. The storage medium of claim **17**, further comprising combining the confidence map for each step of the multi-stage process into an overall confidence map.

19. The storage medium of claim **18**, further comprising communicating the overall confidence map to at least one of a report display, an image reconstruction process, or an automated map process.

20. The storage medium of claim **15**, wherein generating the at least one confidence map includes processing the at least one of the PDFF or R_2^* maps using a threshold to identify spatial locations in the at least one of PDFF or R_2^* maps with at least one of poor quality of signals for PDFF or R_2^* measurements or water-fat swaps.

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